

Feedback Control Of Dynamical Systems Franklin Bing



Feedback Control Of Dynamical Systems

Feedback Control Of Dynamic Systems □. They are closely related. Consider a car driven by a torque of the engine. +. (1) A series of direct measurements of model parameters. H o w e v e r, such a treatment will lead to poor S/N ratio.

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The intent of this chapter is to expand on the design of control systems that will be implemented in a digital computer. The implementation leads to an average delay of half the sample period and to a phenomenon called aliasing, which need to be addressed in the controller design.

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